

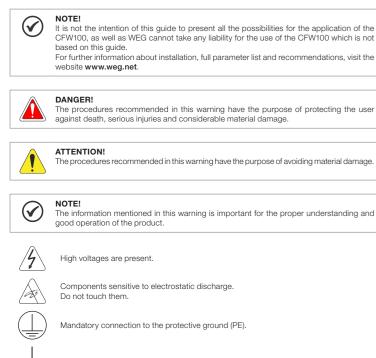
Quick Installation Guide

CFW100 Micro Drive

1 SAFETY INSTRUCTIONS

This quick installation guide contains the basic information necessary to commission the CFW100. It has been written to be used by qualified personnel with suitable training or technical qualification for operating this type of equipment. The personnel shall follow all the safety instructions described in this manual defined by the local regulations. Failure to comply with the safety instructions may result in death, serious injury, and/or equipment damage

2 SAFETY WARNINGS IN THE MANUAL



Connection of the shield to the around,

3 PRELIMINARY RECOMMENDATIONS

DANGER

NOTE!

Always disconnect the main power supply before touching any electrical component associated to the inverter. Several components can remain charged with high voltages or remain in movement (fans) even after the AC power is disconnected or switched off. Wait at least ten minutes after turning off the input power for the complete discharge of the power capacitors. Always connect the grounding point of the inverter to the protection earth (PE). Connectors XCA and XCB do not present USB compatibility; therefore, they cannot be connected to USB doors

These connectors serve only as interface between the CFW100 frequency inverter and its accessories.

 \checkmark

Frequency Inverter may interfere with other electronic equipment. Follow the precautions recommended in manual available in www.weg.net.

Do not perform any withstand voltage test! If necessary, contact the manufacturer.



Electronic boards have components sensitive to electrostatic discharges Do not touch directly on components or connectors. If necessary, first touch the grounding point of the inverter, which must be connected to the protection earth (PE) or use a proper arounding strap

ATTENTION

When the inverter is stored for a long period, it becomes necessary to perform the capacitor reforming. Refer to the procedure recommended in www.weg.net.

4 ABOUT THE CFW100

The CFW100 frequency inverter is a high-performance product which allows speed and torque control of three-phase induction motors. This product provides the user with the options of vector (VVW) or scalar (V/f) control, both programmable according to the application.

5 TERMINOLOGY

	Product and Series		Model I	Dograd of	Hardware	Cotturara		
		Frame Size	Rated Current	Phase Number	Rated Voltage	Protection		Version
E.g.:	CFW100	A	01P6	S	2	20		
suc	CFW100	A	01P6 = 1.6 A	S = single-phase supply	2 = 200240 V			Blank = standard
options		В	02P6 = 2.6 A					Sx =
Available o		С	04P2 = 4.2 A					special software
		20 = IP20					Blank = standard	
		20 = 120					Hx = specia	al hardware

6 RECEIVING AND STORAGE

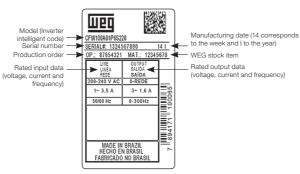
The CFW100 is supplied packed in a cardboard box. There is an identification label affixed to the outside of the package, identical to the one affixed to the side of the inverter

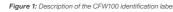
The CEW100 identification label corresponds to the purchased model. Any damage occurred during transportation.

Report any damage immediately to the carrier.

If the CFW100 is not installed soon, store it in a clean and dry location (temperature between -25 °C and 60 °C (-13 °F and 140 °F)), with a cover to prevent dust accumulation inside it.

7 IDENTIFICATION LABEL





8 DIMENSIONS

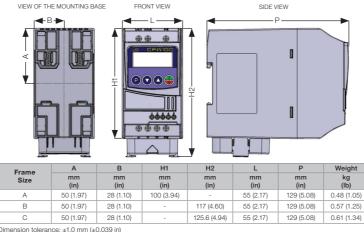


Figure 2: Inverter dimensions for mechanical installation

9 INSTALLATION AND CONNECTION

Environmental Conditions

- Direct exposure to sunlight, rain, high humidity or sea-air.
- Inflammable or corrosive gases or liquids.
- Excessive vibration Dust, metallic particles or oil mist.

Environment conditions permitted for the operation of the inverter

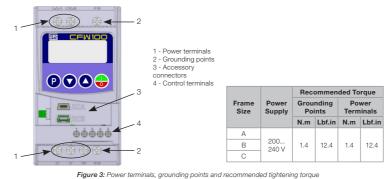
- Temperature surrounding the inverter: 0 °C to 50 °C (32 °F to 122 °F) IP20. For temperatures surrounding the inverter higher than the specifications above, it is necessary to apply of 2 % of current derating for each degree Celsius, limited to an increase of 10 °C (50 °F).
- Air relative humidity: 5 % to 95 % non-condensing.
 Maximum altitude: up to 1000 m (3.300 ft) rated conditions.
- From 1000 m to 4000 m (3.300 ft to 13.200 ft) 1 % of current derating for each 100 m above 1000 m of altitude.
- Pollution degree: 2 (according to EN50178 and UL508C), with non-conductive pollution. Condensation must not originate conduction through the accumulated residues.

10 ELECTRICAL INSTALLATION



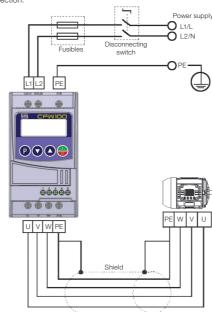
- The following information is merely a guide for proper installation. Comply with applicable local regulations for electrical installations.

 Make sure the AC power supply is disconnected before starting the installation.
- The CFW100 must not be used as an emergency stop device. Provide other devices for that purpose.



10.1 POWER CONNECTIONS

Description of the power terminals: L/L1 and N/L2: AC power supply must be connected to L/L1 and N/L2. U. V and W: connection for the motor. PE: grounding connection.





The CFW100 is suitable for application in a circuit able to supply not more than 30.000 symetric A____ maximum of 240V, when protected by fuses classified as indicated below:

Table 2: List of models of CFW100 series, main electrical specifications

Inverter	umber of Input Phases	Power Supply Rated Voltage	Frame Size	Output Rated Current	Maximum Motor	Greater Greater Breaker		Recommended J Type Fuse	Power Wire Size	Grounding Wire Size
	л Z	[Vrms]		[Arms]	[HP/kW]	[A]	WEG	[A]	mm ² (AWG)	mm ² (AWG)
CFW100A01P6S220	1	200 240	А	1.6	0.25/0.18	5.5	MPW25-3-D063	6	1.5 (16)	2.5 (14)
CFW100B02P6S220	1	200 240	В	2.6	0.5/0.37	9.0	MPW25-3-U010	10	1.5 (16)	2.5 (14)
CFW100C04P2S220	1	200 240	С	4.2	1/0.75	13.5	MPW25-3-U016	17.5	1.5 (16)	2.5 (14)



The inverter must be connected to a protective ground (PE). Use a minimum wire gauge for ground connection equal to the indicated in Table 2.

- Connect the inverter grounding connections to a ground bus bar, to a single ground point or to a common grounding point (impedance $\leq 10 \Omega$).
- The neuter conductor of the line that feeds the inverter must be solidly grounded; however this conductor must not be used to around the inverter.
- Do not share the grounding wiring with other equipment that operate with high currents (e.g.: high voltage motors, welding machines, etc.).



The wire gauges listed in Table 2 are guiding values. Installation conditions and the maximum permitted voltage drop must be considered for the proper wiring sizing.

10.2 CONTROL CONNECTIONS

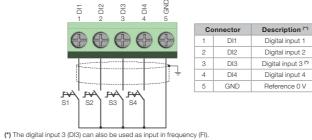


Figure 5: Signals of control card connector of the C100A-20

For the correct connection of the control, use:

1. Gauge of the cables: 0.5 mm² (20 AWG) to 1.5 mm² (14 AWG). 2. Maximum torque: 0.5 N.m (4.50 lbf.in).

- 3. Wiring of the connector of the control board with shielded cable and separated from the other wiring
- (power, command in 110 V / 220 Vac, etc.)

10.3 INSTALLATIONS ACCORDING TO EUROPEAN DIRECTIVE OF ELECTROMAGNETIC COMPATIBILITY

The CFW100 inverter series, when properly installed, meet the requirements of the directive of the electromagnetic compatibility. These inverters were developed for professional applications only. Therefore, the emission limits of

harmonic currents by the standards EN 61000-3-2 and EN 61000-3-2/A 14.

10.3.1 Conformal Installation

- 1. Shielded output cables (motor cables) with shield connected at both ends, motor and inverter, by means of a low impedance to high frequency connection. Maximum motor cable length and conduced and radiated emission levels according to Table 5. For more information (RFI filter commercial reference, motor cable length and emission levels) refer to the Table 5
- 2. Shielded control cables, keeping the separation distance from other cables according to Table 3.2 the user's manual.
- 3. Grounding of the inverter according to instruction of the 3.2.4 Grounding Connections the user's manual. Grounded power supply.
 The inverter and external filter must be mounted on a common metal plate.
- . The wiring between filter and inverter must be as short as possible
- 7. The grounding must be done according to recommendation of the CFW100 user's manual.
- 8. Use short wiring to ground the external filter or inverter. Ground the mounting plate using a flexible braid as short as possible. Flat conductors have lower impedance at high frequencies.
- 10. Use sleeves for cable conduits whenever possible.

10.3.2 Emission and Immunity Levels

Table 3: Emission and immunity levels

EMC Phenomenon	Basic Standard	Level
Emission:		
Mains terminal disturbance voltage Frequency range: 150 kHz to 30 MHz)	IFC/FN 61800-3	It depends on the inverter model on the length of the
Electromagnetic radiation disturbance Frequency Range: 30 MHz to 1000 MHz)	IEC/EN 01000-3	motor cable. Refer to Table 5
Immunity:		
Electrostatic discharge (ESD)	IEC 61000-4-2	4 kV for contact discharge and 8 kV for air discharge
Fast transient-Burst	IEC 61000-4-4	2 kV / 5 kHz (coupling capacitor) input cables 1 kV / 5 kHz control cables and remote HMI cables 2 kV / 5 kHz (coupling capacitor) motor cables
Imunidade conduzida ("Conducted radio- frequency common mode")	IEC 61000-4-6	0.15 to 80 MHz; 10 V; 80 % AM (1 kHz) Motor, control and HMI cables
Surges	IEC 61000-4-5	1.2/50 μs, 8/20 μs 1 kV line-to-line coupling 2 kV line-to-ground coupling
Radio-frequency electromagnetic field	IEC 61000-4-3	80 to 1000 MHz 10 V/m 80 % AM (1 kHz)

Definition of Standard IEC/EM 61800-3: "Adjustable Speed Electrical Power Drives Systems"

Environments

First Environment: environments that include domestic installations, as well as establishments directly connected without intermediate transformer to a low-voltage power supply network which supplies buildings used for domestic purposes.

Second Environment: includes all establishments other than those directly connected to a low voltage power supply network that supplies buildings used for domestic purposes.

Categories

Category C1: inverters with a voltage rating less than 1000 V and intended for use in the First Environment. Category C2: inverters with a voltage rating less than 1000 V intended for use in the First Environment, not provided with a plug connector or movable installations. They must be installed and commissioned by a professional



NOTE!

A professional is a person or organization familiar with the installation and/or commissioning of inverters, including their EMC aspects.

Category C3: inverters with a voltage rating less than 1000 V and intended for use in the Second Environment only (not designed for use in the First Environment).

10.3.3 Characteristics of the RFI Filter

The CFW100 inverters, when installed with external filter, are used to reduce the conducted from the inverter to the power line in the high frequency band (>150). It is necessary to meet the maximum levels of conducted emission of electromagnetic compatibility standards, such as EN 61800-3 and EN 55011. For further information about the RFI filter model, refer to Table 4. The figure below demonstrate the connection of the filter to the inverter

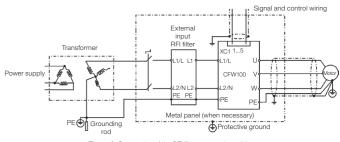


Figure 6: Connection of the RFI filter - general conditions

Table 4: External REI filter models for CEW100

WEG Item Name Description External RFI filter kit WEG 13128410 CFW100-KFABC Filter B84142A0010R000 Epcos (*)

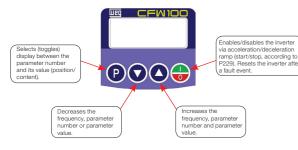
(*) For Electrodiagnostica Radiation Disturbance use choke (T60006- L2016-W403 - VACUUMSCHMELZE)

Inverter Model		- Conducted Emission Ler	Radiated Emission Category C3		
		Category C2 Category C3			
1	CFW100A01P6S220				
2	CFW100B02P6S220	1 m (39 in)	10 m (393 in)	10 m (393 in)	
3	CFW100C04P2S220				

10.4 ACCESSORIES

The accessories are hardware resources that can be added in the application with the CFW100. The accessories are incorporated to the inverters in an easy and quick way by using the concept "Plug and Play". The accessory must be installed or modified with the inverter de-energized. They may be ordered separately, and are sent in their own package containing the components and manuals with detailed instructions for their installation, operation and setting.

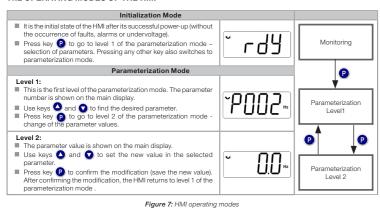
11 USE OF THE KEYPAD TO OPERATE THE INVERTER



11.1 INDICATIONS OF DISPLAY



11.2 OPERATING MODES OF THE HMI



12 START-UP PREPARATION

DANGER!
Always disconnect the main power supply before making any connection.

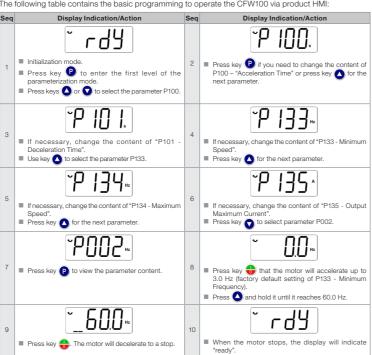
1. Check if the power, grounding and control connections are correct and firm.

- 2. Remove all the materials left behind from the installation work from inside the inverter or the cabinet.
- Verify the motor connections and if its voltage and current are within the inverter rated value.
 Mechanically uncouple the motor from the load. If the motor cannot be uncoupled, make sure that any speed direction (forward or reverse) will not result in personnel injury and/or equipment damage.
- 5. Close the inverter or cabinet covers.
- 6. Measure the power supply and verify if it is within the allowed range. 7. Apply power to the input: close the input disconnecting switch.
- 8. Check the result of the first time power-up: The HMI display indicates:

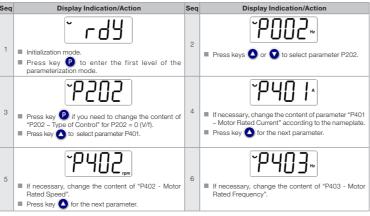


12.1 BASIC APPLICATION

The following table contains the basic programming to operate the CFW100 via product HMI:



12.2 TYPE OF CONTROL V/f (P202 = 0)



13 TECHNICAL SPECIFICATIONS

POWER DATA

- Power Supply:
- Tolerance: -15 % to +10 %.
 Frequency: 50/60 Hz (48 Hz to 62 Hz).
- Phase imbalance: ≤ 3 % of the rated phase-to-phase input voltage.
 Overvoltage according to Category III (EM 61010/UL 508C).
- Transient voltages according to Category III.
 Maximum of 10 connections per hour (1 every 6 minutes).
- Typical efficiency: ≥ 97 %.
- 14 ELECTRONICS/GENERAL DATA

Table 6: Electronics/general data

Control	Method	Types of control: - V/f (Scalar) - VVW: voltage vector control PWM SVM (Space Vector Modulation)
	Output frequency	0 to 300 Hz, resolution of 0.1 Hz
Performance	V/f Control	 Speed regulation: 1 % of the rated speed (with slip compensation) Speed variation range: 1:20
	Vector control (VVW)	 Speed regulation: 1 % of the rated speed Speed variation range: 1:30
Inputs	Digital	4 isolated inputs Maximum input voltage of 30 Vdc Input current: - 11 mA Maximum input current: -20 mA
Safety	Protection	Output overcurrent/short-circuit Under/overoltage Motor overload Overtemperature in the power module (IGBTs) Fault / external alarm Programming error
Integral keypad (HMI)	Standard keypad	4 keys: Start/Stop, Up arrow, Down arrow and Programming LCD Display View/edition of parameters Indication accuracy: - current: 5 % of the rated current - speed resolution: 0.1 Hz
Enclosure	IP20	Frame Sizes A. B and C

15

15 CONSIDER	RED STANDARDS	Param.	Description	Adjust	able Range	Factory Setting	Prop.
		P222	REM Reference Sel.	See options in P221		2	cfg
Safety standards	Table 7: Considered standards UL 508C - power conversion equipment UL 508C - insulation coordination including clearances and creepage distances for electrical equipment EN51800-5-1 - safety requirements electrical, thermal and energy EN 507078 - electronic equipment for use in power installations EN 60204-1 - safety of machinery, Electrical equipment of machines. Part 1: general requirements Note: the final assembler of the machine is responsible for installing a safety stop device and a supply disconnecting device EN 60146 (IEC 146) - semiconductor converters EN 61800-2- adjustable speed electrical power drive systems - Part 2: general requirements - rating specifications for low voltage adjustable frequency AC power drive systems	P223	LOC Rotation Sel.	0 = Always FWD 6 = Serial/USB (REV) 1 = Always REV 7 to 8 = Not Used 2 = Not Used 9 = CO/DN (FWD) 3 = Not Used 10 = CO/DN (REV) 4 = Dlx 11 = Not Used 5 = Serial/USB (FWD) 12 = SoftPLC		0	cfg
		P263	DI1 Input Function	0 = Not Used 1 = Run/Stop 2 = General Enable 3 = Ouick Stop 4 = Forward Run 5 = Reverse Run 6 = Start 7 = Stop 8 = FWD/REV 9 = LOC/REM 10 = JOG 11 = Increase E.P. 12 = Decelerate E.P. 13 = Multispeed 14 = 2 rd Ramp 15 to 17 = Not Used 18 = No Ext. Alarm 19 = No Ext. Fault 20 = Reest 21 to 23 = Not Used 24 = Disab. Fiving Start	$\begin{array}{l} 25 = \operatorname{Regul. DC Link} \\ 26 = \operatorname{Lock Prog.} \\ 27 \text{ to } 31 = \operatorname{Not Used} \\ 32 = 2^{24} \operatorname{Ramp E.P. Ac.} \\ 34 = 2^{24} \operatorname{Ramp E.P. Ac.} \\ 35 = 2^{24} \operatorname{Ramp F.P. WRun} \\ 36 = 2^{24} \operatorname{Ramp F.W Run} \\ 36 = 2^{24} \operatorname{Ramp Few Run} \\ 37 = \operatorname{Turn ON / Ac. E.P.} \\ 38 = \operatorname{De. E.P. / Turn OFF} \\ 39 = \operatorname{Stop} \\ 0 = \operatorname{Stafety Switch} \\ 41 = \operatorname{Function 1 Application} \\ 42 = \operatorname{Function 2 Application} \\ 43 = \operatorname{Function 3 Application} \\ 44 = \operatorname{Function 3 Application} \\ 45 = \operatorname{Function 3 Application} \\ 45 = \operatorname{Function 3 Application} \\ 46 = \operatorname{Function 3 Application} \\ 47 = \operatorname{Function 3 Application} \\ 48 = \operatorname{Function 3 Application} \end{array}$	1	cfg
Mechanical standards	 EN 60529 - degrees of protection provided by enclosures (IP code) UL 50 - enclosures for electrical equipment 						
Electromagnetic compatibility (EMC) standards ^(*)	Etromagnetic mpatibility Etromagnetic Etromagnetic mpatibility MC) Etromagnetic Etromagnetic Etromagnetic						
	EN 61000-4-5 - electromagnetic compatibility (EMC) - part 4: testing and measurement techniques	P264	DI2 Input Function	See options in P263		8	cfg
	- section 5: surge immunity test.	P265	DI3 Input Function	See options in P263		0	cfg
	EN 61000-4-6 - electromagnetic compatibility (EMC) - part 4: testing and measurement techniques - section 6: immunity to conducted disturbances, induced by radio-frequency fields.	P266	DI4 Input Function	See options in P263		0	cfg
) Standards met wi	- section 6. Infinitulity to conducted disturbances, induced by radio-frequency fields.	P295	Inv. Rated Current	1.6 to 15.2 A		According to inverter model	ro
IG MAIN PAREMETERS		P296	Line Rated Voltage	0 to 1 = Reserved 2 = 200 - 240 V		2	ro, cfg
IO WAIN PAR	EWIETERS	P297	Switching Frequency	2.5 to 15.0 kHz		5.0 kHz	
		P401	Motor Rated Current	0.0 to 10.0 A		1.4 A	cfg
ne table below o	contains the mains parameters of the CFW100.	P402	Motor Rated Speed	0 to 9999 rpm		1720 (1310) rpm	cfg
		P403	Motor Rated Frequency	0 to 300 Hz		60 (50) Hz	cfg

NOTE \checkmark

ro = read only parameter. V/f = parameter available in V/f mode.

cfg = configuration parameter, value can only be changed with the motor stopped.

Param.	Description	Adius	table Range	Factory Setting	Prop
Param. P000	Access to Parameters	0 to 9999	lable Hallye	Factory Setting	нор
P000	Speed Reference	0 to 9999		1	ro
P001 P002					
	Output Speed (Motor)	0 to 9999			ro
P003	Motor Current	0.0 to 10.0 A			ro
P004	DC Link Voltage (Ud)	0 to 524 V			ro
P005	Output Frequency (Motor)	0.0 to 300.0 Hz			ro
P006	Inverter Status	0 = Ready	3 = Fault		ro
		1 = Run	4 = Not Used		
P007	Output Voltage	2 = Undervoltage 0 to 240 V	5 = Configuration		ro
P011	Active Current	-10.0 to 10.0 A			ro
P012	DI8 to DI1 Status	0 to FF (hexa)	Bit 4 = DI5 Bit 5 = DI6		ro
		Bit 0 = DI1 Bit 1 = DI2	Bit 6 = DI7		
		Bit 2 = DI3	Bit $7 = DI8$		
		Bit 3 = DI4			
P022	FI Value in Hz	1 to 3000 Hz			ro
P023	Main SW Version	0.00 to 99.99			ro
P030	Module Temperature	-200.0 to 200.0 °C			ro
P037	Motor Overload Ixt	0.0 to 100.0 %			ro
P047	CONFIG Status	0 to 999			ro
P047	Present Alarm	0 to 999			ro
P048 P049				-	-
	Present Fault	0 to 999			ro
P050	Last Fault	0 to 999			ro
P100	Acceleration Time	0.1 to 999.9 s		5.0	
P101	Deceleration Time	0.1 to 999.9 s		10.0	
P120	Speed Ref. Backup	0 = Inactive		1	
		1 = Active			
Bioi	D.C	2 = Backup by P121		0.011	
P121	Reference via HMI	0.0 to 300.0 Hz		3.0 Hz	
P124	Multispeed Ref. 1	-300.0 to 300.0 Hz		3.0 Hz	
P125	Multispeed Ref. 2	-300.0 to 300.0 Hz		10.0 (5.0) Hz	
P126	Multispeed Ref. 3	-300.0 to 300.0 Hz		20.0 (10.0) Hz	
P127	Multispeed Ref. 4	-300.0 to 300.0 Hz		30.0 (20.0) Hz	
P128	Multispeed Ref. 5	-300.0 to 300.0 Hz		40.0 (30.0) Hz	
P129	Multispeed Ref. 6	-300.0 to 300.0 Hz		50.0 (40.0) Hz	
P130	Multispeed Ref. 7	-300.0 to 300.0 Hz		60.0 (50.0) Hz	
P131	Multispeed Ref. 8	-300.0 to 300.0 Hz		66.0 (55.0) Hz	
P133	Minimum Frequency	0.0 to 300.0 Hz		3.0 Hz	
P134	Maximum Frequency	0.0 to 300.0 Hz		66.0 (55.0) Hz	
P135	Maximum Output Current	0.0 to 10.0 A		. ,	
P135 P136				1.5xl _{nom}	V/f
	Manual Torque Boost	0.0 to 30.0 %		0.0 %	
P137	Automatic Torque Boost	0.0 to 30.0 %		0.0 %	V/f
P138	Slip Compensation	-10.0 to 10.0 %		0.0 %	V/f
P139	Output Current Filter	0 to 9.999 s		0.005 s	
P140	Slip Com. Filter	0 to 9.999 s		0.5 s	VVV
P142	Maximum Output Voltage	0.0 to 100.0 %		100.0 %	cfg, V
P143	Intermediate Output	0.0 to 100.0 %		50.0 %	cfg, V
-	Voltage				5, 1
P145	Field Weakening Start	0.0 to 300.0 Hz		60.0 (50.0) Hz	cfg, V
	Frequency				
P146	Intermediate Frequency	0.0 to 300.0 Hz		30.0 (25.0) Hz	cfg, V
P156	Overload Current	0.1 to 2xl _{nom}		1.2xl _{nom}	
P202	Type of Control	0 = V/f		0	cfg
		1 = V/f Quadratic			
		2 to 4 = Not Used			
P204	Load/Save Parameters	5 = VVW 0 to 4 = Not Used	9 = Save User	0	ofe
F 204	LUQU/GAVE FAI AITIELETS	5 = Load 60 Hz	9 = Save User 10 = Not Used		cfg
		6 = Load 50 Hz	11 = Load Default SoftPLC		
		7 = Load User	12 to 13 = Reserved		
		8 = Not Used			
P220	LOC/REM Selection	0 = Always Local	6 = Serial/USB (REM)	0	cfg
	Source	1 = Always Remote	/ to 8 = Not Used		
		2 to 3 = Not Used	9 = CO/DN (LOC)		
		4 = Dlx	10 = CO/DN (REM)		
P221	LOC Deferon C-l		11 = SoftPLC	0	-£.
P221	LOC Reference Sel.	0 = HMI Keys 1 = Al1	10 = Not Used 11 = CO/DN	0	cfg
		2 to 3 = Not Used	12 = SoftPLC		
		4 = FI	13 = Not Used		
		5 to 6 = Not Used	14 = AI1 > 0		
		7 = E.P.	15 to 16 = Not Used		
		8 = Multispeed	17 = FI > 0		
		9 = Serial/USB		1	

17 FAULTS AND ALARMS

Most common faults and alarms

Fault / Alarm	Description	Possible Causes
A046 Motor Overload	Motor overload alarm	 Settings of P156 is too low for the used motor Overload on the motor shaft
A050 Power Module Overtemperature	Overtemperature alarm from the power module temperature sensor (NTC)	 High temperature at IGBTs (P030 > 110 °C) High ambient temperature around the inverter (>50 °C (> 122 °F)) and high output current Blocked or defective fan Heatsink is too dirty, preventing the air flow
A090 External Alarm	External alarm via DIx (option "No External Alarm" in P26x)	Wiring on DI1 to DI4 inputs are open or have poor contact
A700 Remote HMI Communication Fault	No communication with remote HMI, but here is frequency command or reference for this source	 Check if the communication interface with the HMI is properly configured in parameter P312 HMI cable disconnected
F021 Undervoltage on the DC Link	Undervoltage fault on the intermediate circuit	 Wrong voltage supply; check if the data on the inverter label comply with the power supply and parameter P296 Supply voltage to low, producing voltage on the DC link below the minimum value (in P004): Ud < 200 Vdc in 200 / 240 Vac Phase fault in the input Fault in the pre-charge circuit
F022 Overvoltage on the DC Link	Overvoltage fault on the intermediate circuit	 Wrong voltage supply; check if the data on the inverter label comply with the power supply and parameter P296 Supply voltage is too high, producing voltage on the DC link above the maximum value (in P004); Ud > 410 Vdc in 200 / 240 Vac Load inertia is too high or deceleration ramp is too fast P151 setting is too high
F031 Fault of communication with the accessory	Main control cannot establish the communication link with accessory	Accessory damaged Poor connection of the accessory Problem in the identification of the accessory; refer to P027
F051 IGBTs Overtemperatures	Overtemperature fault measured on the temperature sensor of the power pack	 High temperature at IGBTs (P030 > 120 °C) High ambient temperature around the inverter (>50 °C (>122 °F)) and high output current Blocked or defective fan Heatsink is too dirty, preventing the air flow
F070 Overcurrent/ Shortcircuit	Overcurrent or short-circuit on the output, DC link or braking resistor	Short-circuit between two motor phases IGBTs module in short-circuit or damaged Start with too short acceleration ramp Start with motor spinning without the Flying Start function
F072 Motor Overload	Motor overload fault (60 s in 1.5 x Inom)	 P156 setting is too low in relation to the motor operating current Overload on the motor shaft
F080 CPU Fault (Watchdog)	Fault related to the supervision algorithm of the inverter main CPU	 Electric noise Inverter firmware fault
F081 Fault on the Save User function	Fault in the attempt to save the user parameter table	 Attempt to save (P204 = 9) more than 32 parameters (with values different from the factory default) on the User parameter table The function Saves User is blocked
F082 Fault in the Copy Function (MMF)	Fault in the copy of parameters	Attempt to copy the parameters from the Flash Memory Module to the inverter with different software versions
F084 Auto-diagnosis Fault	Fault related to the automatic identification algorithm of the inverter hardware	 Poor contact in the connection between the main control anthe power pack Hardware not compatible with the firmware version Defect on the internal circuits of the inverter
F091 External Fault	External fault via Dlx ("No External Fault" in P26x)	Wiring on DI1 to DI4 inputs are open or have poor contact
F701 Remote HMI communication fault	No communication with the remote HMI; however, there is command or frequency reference for this source	Check that the HMI communication interface is properly configured in parameter P312 HMI cable disconnected

